

Chapter 15; Periodic Motion

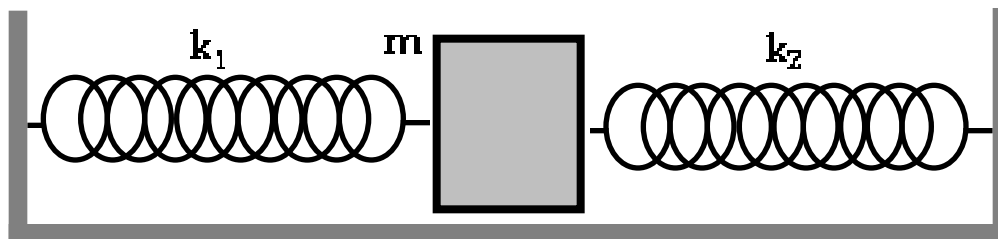
15.9, 11, 12, 15, 20, 25, 31, 34, 35

15.9 This is an excellent one to solve with a spreadsheet:

$$f = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$$

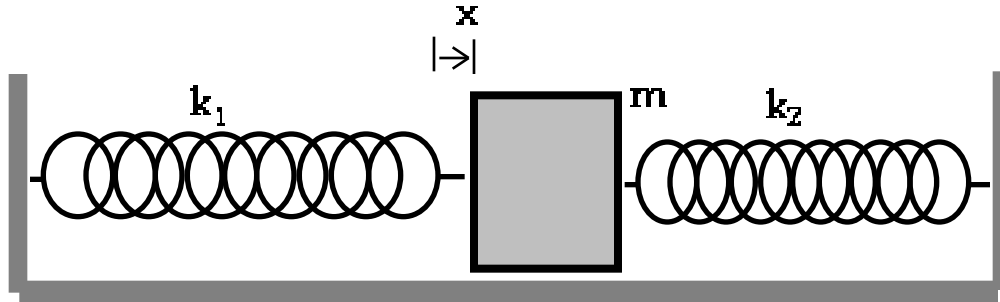
	A	B	C	D	E
1			"=SQRT(C4/B4)/2/3.14159		
2		Mass	Spg Const	Frequency	
3		(kg)	(N/m)	(Hz = 1/s)	
4	a	1	2.5	0.2516	Hz
5	b	2.5	1	0.1007	Hz
6	c	3	7.2	0.2466	Hz
7	d	50	100	0.2251	Hz
8	e	80	200	0.2516	Hz
9	f	100	250	0.2516	Hz
10	g	120	250	0.2297	Hz
11	h	200	500	0.2516	Hz

15.11 $f = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$ where k in this equation is the "effective spring constant", the spring constant of a single spring that has the same effect as the combination of springs in the diagram.



With this arrangement, a displacement of x causes a force of

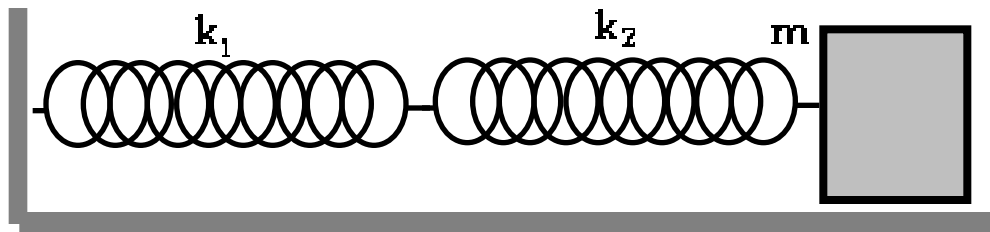
$F_1 = -k_1x$ due to the spring on the left and a force of $F_2 = -k_2x$ due to the spring on the right.



The net force, then, is $F_{\text{net}} = F_1 + F_2 = -k_1x - k_2x = -(k_1 + k_2)x$. Since the effective spring constant, k_{eff} is the constant is $F_{\text{net}} = -k_{\text{eff}}x$, we can see that

$$k_{\text{eff}} = k_1 + k_2$$

The next arrangement of springs is a little more "tricky" or more interesting:



When the mass is moved a distance x , spring #1 stretches a distance x_1 and spring #2 stretches a distance x_2 with

$$x = x_1 + x_2$$

That is, the two springs need not be stretched (or compressed) the same amount at all. However, the force exerted by each spring must be the same. That is,

$$F_1 = F_2$$

or

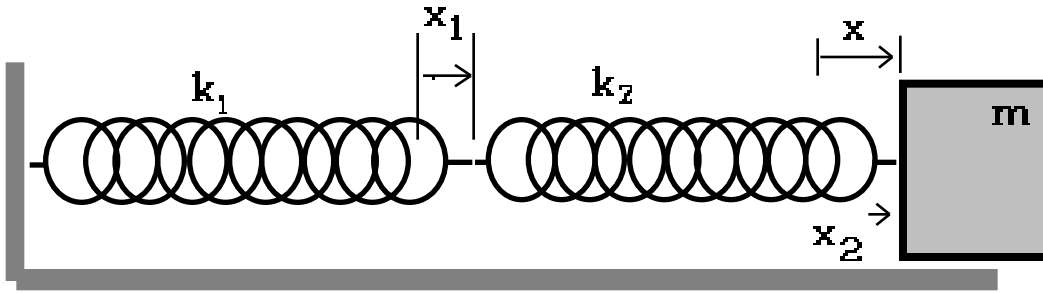
$$k_1 x_1 = k_2 x_2$$

or

$$x_1 = (k_2/k_1) x_2$$

or

$$x_2 = (k_1/k_2) x_1$$



To determine the "effective spring constant", we must write the force in the form of

$$F = -k_{\text{eff}} x$$

We have

$$F = -k_1 x_1$$

and

$$x = x_1 + x_2$$

$$x = x_1 + (k_1/k_2) x_1$$

$$x = [1 + (k_1/k_2)] x_1$$

$$x_1 = \frac{x}{1 + (k_1/k_2)}$$

Therefore,

$$F = k_1 \left(\frac{x}{1 + (k_1/k_2)} \right)$$

$$F = k_1 \left(\frac{x}{(k_2/k_2) + (k_1/k_2)} \right)$$

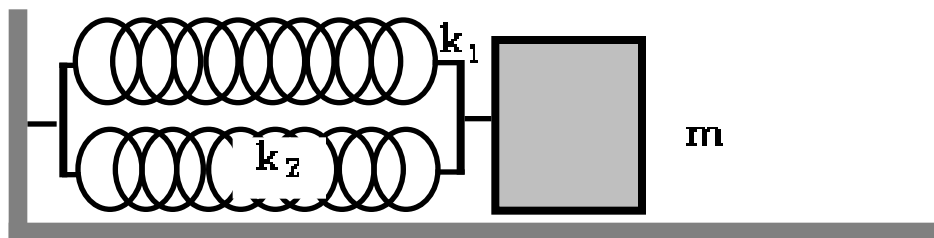
$$F = - \left(\frac{k_1 k_2}{k_1 + k_2} \right) x$$

Therefore,

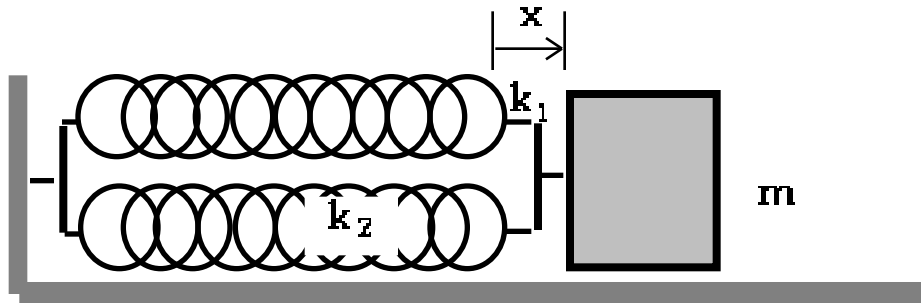
$$k_{\text{eff}} = \frac{k_1 k_2}{k_1 + k_2}$$

which can also be written as

$$\frac{1}{k_{\text{eff}}} = \frac{1}{k_1} + \frac{1}{k_2}$$



The third arrangement of springs is actually fairly easy and straightforward. With this arrangement, a displacement of x causes a force of $F_1 = -k_1x$ due to spring #1 and a force of $F_2 = -k_2x$ due to spring #2. The stretch of each spring is the same as the displacement of the mass.



The net force, then, is $F_{\text{net}} = F_1 + F_2 = -k_1x - k_2x = -(k_1 + k_2)x$. Since the effective spring constant, k_{eff} is the constant is $F_{\text{net}} = -k_{\text{eff}}x$, we can see that

$$k_{\text{eff}} = k_1 + k_2$$

15.12 $W = (1/2) k x^2$
 $W = (1/2) (80 \text{ N/m}) (0.15 \text{ m})^2$
 $W = 0.9 \text{ J}$

15.15 $W = PE = (1/2) k A^2 = (1/2) (50 \text{ N/m}) (0.1 \text{ m})^2 = 0.25 \text{ J}$
 As the mass moves through equilibrium, $x = 0$, so it has zero potential energy and its total energy is now KE,
 $KE = (1/2) m v^2 = (1/2) (0.2 \text{ kg}) v^2 = 0.25 \text{ J} = E$
 $v^2 = 2.5 \text{ m}^2/\text{s}^2$

$$v = 1.58 \text{ m/s}$$

15.20 $E = PE_{\text{max}} = (1/2) k A^2$
 $A = 12 \text{ cm} = 0.12 \text{ m}$
 $E = (1/2) (k) (0.12 \text{ m})^2$
 $E = KE + PE = \frac{1}{2} m v^2 + \frac{1}{2} k x^2$
 $E = (1/2) m (0.2 \text{ m/s})^2 + (1/2) k (0.08 \text{ m})^2 = (1/2) (k) (0.12 \text{ m})^2 = E$
 $m (0.2 \text{ m/s})^2 = k (0.12 \text{ m})^2 - k (0.08 \text{ m})^2$
 $(m/k)(0.2 \text{ m/s})^2 = (0.12 \text{ m})^2 - (0.08 \text{ m})^2$
 $(m/k)(0.04) (\text{m/s})^2 = (0.0144 - 0.0064) \text{ m}^2 = 0.0080 \text{ m}^2$

$$(m/k) = 0.2 (1/s^2)$$

$$T = 2 \sqrt{\frac{m}{k}}$$

$$T = 2.8 \text{ sec}$$

15.25 These multiple-data-set problems are good ones to solve with a spreadsheet. This is basically energy conservation,

$$E = (1/2) k A^2 = (1/2) k x^2 + (1/2) m v^2$$

$$k A^2 = k x^2 + m v^2$$

$$m v^2 = k (A^2 - x^2)$$

$$v^2 = (m/k) (A^2 - x^2)$$

$$v = \sqrt{\frac{k}{m} (A^2 - x^2)}$$

So this will be the formula we put in the spreadsheet:

	A	B	C	D	E	F
1			'=SQRT((C4/B4)*(D4*D4-E4*E4))			
2		mass	spg cnst	Amplitude	position	velocity
3		(kg)	(N/m)	(m)	(m)	(m/s)
4	a	0.18	3.5	0.2	0.1	0.7638
5	b	0.18	3.5	0.2	0.15	0.5833
6	c	0.28	3.5	0.2	0.18	0.3082
7	d	0.35	5	0.25	0.05	0.9258
8	e	0.35	5.5	0.25	0.1	0.9083
9	f	0.5	5.5	0.25	0.1	0.7599
10	g	0.5	5.5	0.25	0.15	0.6633
11	h	0.5	5.5	0.3	0.15	0.8617

15.31 $f = \frac{1}{2} \sqrt{\frac{k}{m}}$

$$f^2 = (1/4) \frac{k}{m}$$

$$k = 4 f^2 m$$

$$k = 4 [2 (1/2)]^2 (0.5 \text{ kg})$$

$$k = 79 \text{ kg/s}^2$$

$$k = 79 \text{ N/m}$$

$$15.34 \quad T = 2.00 \text{ s}$$

$$T = 2 \sqrt{\frac{l}{g}}$$

$$T^2 = 4 \frac{l}{g}$$

$$l = \frac{1}{4} T^2 g$$

$$l = 0.993 \text{ m}$$

$$15.35 \quad T = 2 \sqrt{\frac{l}{g}}$$

$$T = 2 \sqrt{\frac{1.0 \text{ m}}{9.8 \text{ m/s}^2}}$$

$$T = 2.007 \text{ seconds}$$

(That is, this is almost a "seconds pendulum").